Fundamentals of Engineering Exam Review Series

Mathematics

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Overview

- 110 multiple choice questions total
- 5 hrs 20 min to answer questions
- slightly less than 3 minutes per question

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- 5 hrs 20 min to answer questions
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Discipline	Number of math questions	% of test		
Mechanical	6-9	5.5% - 8%		
Electrical & Computer	11-17	10% - 15.5%		
Civil	7-11	6% - 10%		
Chemical	8-12	7% - 11%		
Other	12-18	11% - 16%		

Mathematics Content

Discipline	Algebra & Trigonometry	Analytic Geometry	Calculus	Linear Algebra	Vector Analysis	Differential Equations	Numerical Methods	Complex Numbers	Discrete Mathematics	Roots of Equations
Mechanical		•	•	•	•	•	•			
Electrical & Computer	~	•	~	~	•	~		•	~	
Civil		•	~		•					~
Chemical		•	~			~				~
Other	~	~	•	~		~	~			

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Mathematics Content

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Mechanical		~	•	~	~	~	~			
Electrical & Computer	~	~	~	~	~	~		•	~	
Civil		~	~		~					~
Chemical		~	~			~				~
Other	~	~	~	~		~	~			

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Permitted Calculators

- Casio FX-115 models
- HP 33 models
- HP 35 models
- TI-30x models
- TI-36x models

Outline

- I. Analytic Geometry
- II. Algebra
- III. Trigonometry
- IV. Calculus
- V. Differential Equations
- VI. Linear Algebra and Vectors

Analytic Geometry

- Equations and Curves
- Perimeter, Area, and Volume

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- Conic Sections
 - Parabola
 - Hyperbola
 - Ellipse
 - Circle

Straight Line (pg. 18)

STRAIGHT LINE

The general form of the equation is Ax + By + C = 0The standard form of the equation is y = mx + b, which is also known as the *slope-intercept* form. The *point-slope* form is $y - y_1 = m(x - x_1)$ Given two points: slope, $m = (y_2 - y_1)/(x_2 - x_1)$ The angle between lines with slopes m_1 and m_2 is $\alpha = \arctan[(m_2 - m_1)/(1 + m_2 \cdot m_1)]$ Two lines are perpendicular if $m_1 = -1/m_2$ The distance between two points is

$$d = \sqrt{(y_2 - y_1)^2 + (x_2 - x_1)^2}$$

Straight Line

A line goes through the point (4, -6) and is perpendicular to the line y = 4x + 10. What is the equation of the line?

(A)
$$y = -\frac{1}{4}x - 20$$

(B)
$$y = -\frac{1}{4}x - 5$$

(C)
$$y = \frac{1}{5}x + 5$$

(D)
$$y = \frac{1}{4}x + 5$$

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(C) $y = \frac{1}{5}x + 5$
(D) $y = \frac{1}{4}x + 5$



13 **Straight Line** What is the general form of the equation for a line whose x-intercept is 4 and y-intercept is -6?(A) 2x - 3y - 18 = 0(B) 2x + 3y + 18 = 0(C) 3x - 2y - 12 = 0(D) 3x + 2y + 12 = 0





Tangent Line to Circle

A circle with a radius of 5 is centered at the origin.



What is the standard form of the equation of the line tangent to this circle at the point (3, 4)?

(A)
$$x = \frac{3}{3}y - \frac{1}{4}$$

(B) $y = \frac{3}{4}x + \frac{25}{4}$
(C) $y = \frac{-3}{4}x + \frac{9}{4}$

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Tangent Line to Circle

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What is the standard form of the equation of the line tangent to this circle at the point (3, 4)?

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(A)
$$x = \frac{3}{3}y - \frac{30}{4}$$

(B) $y = \frac{3}{4}x + \frac{25}{4}$
(C) $y = \frac{-3}{4}x + \frac{9}{4}$





Conic Sections (pgs. 22-23)

Conic Section Equation

The general form of the conic section equation is $Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$ where not both *A* and *C* are zero. If $B^2 - 4AC < 0$, an *ellipse* is defined. If $B^2 - 4AC > 0$, a *hyperbola* is defined. If $B^2 - 4AC = 0$, the conic is a *parabola*. If A = C and B = 0, a *circle* is defined. If A = B = C = 0, a *straight line* is defined. $x^2 + y^2 + 2ax + 2by + c = 0$

is the normal form of the conic section equation, if that conic section has a principal axis parallel to a coordinate axis. h = -a; k = -b $r = \sqrt{a^2 + b^2 - c}$

If $a^2 + b^2 - c$ is positive, a *circle*, center (-a, -b). If $a^2 + b^2 - c$ equals zero, a *point* at (-a, -b). If $a^2 + b^2 - c$ is negative, locus is *imaginary*.



 $(y-k)^2 = 2p(x-h)$; Center at (h, k)is the standard form of the equation. When h = k = 0, Focus: (p/2, 0); Directrix: x = -p/2

Case 2. Ellipse *e* < 1:



Focus: $(\pm ae, 0)$; Directrix: $x = \pm a/e$

Case 3. Hyperbola e > 1:



is the standard form of the equation. When h = k = 0,

Eccentricity: $e = \sqrt{1 + (b^2/a^2)} = c/a$ $b = a\sqrt{e^2 - 1};$ Focus: $(\pm ae, 0);$ Directrix: $x = \pm a/e$

Case 4. Circle e = 0:

 $(x-h)^2 + (y-k)^2 = r^2$; Center at (h, k) is the standard form of the equation with radius





What kind of conic section is described by the following equation?

$$4x^2 - y^2 + 8x + 4y = 15$$

- (A) circle
- (B) ellipse
- (C) parabola
- (D) hyperbola



What is the equation of a parabola with a vertex at (4, 8) and a directrix at y=5?

(A)
$$(x-8)^2 = 12(y-4)$$

(B)
$$(x-4)^2 = 12(y-8)$$

(C)
$$(x-4)^2 = 6(y-8)$$

(D)
$$(y-8)^2 = 12(x-4)$$

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D)
$$(y-8)^2 = 12(x-4)$$

What is the equation of the ellipse with center at (0,0) that passes through the points (2,0), (0,3), and (-2,0)?

(A)
$$\frac{x^2}{9} - \frac{y^2}{4} = 1$$

(B)
$$\frac{x^2}{4} - \frac{y^2}{9} = 1$$

(C)
$$\frac{x^2}{9} + \frac{y^2}{4} = 1$$

(D)
$$\frac{x^2}{4} + \frac{y^2}{9} = 1$$

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$$\frac{x^2}{9} - \frac{y^2}{4} = 1$$

(B)
$$\frac{x^2}{4} - \frac{y^2}{9} = 1$$

(C)
$$\frac{x^2}{9} + \frac{y^2}{4} = 1$$

(D)
$$\frac{x^2}{4} + \frac{y^2}{9} = 1$$

What is the equation of the circle passing through the points (0,0), (0,4), and (-4,0)? (A) $(x-2)^2 + (y-2)^2 = \sqrt{8}$ (B) $(x-2)^2 + (y-2)^2 = 8$ (C) $(x+2)^2 + (y-2)^2 = 8$ (D) $(x+2)^2 + (y+2)^2 = \sqrt{8}$

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What is the equation of the circle passing through the points (0,0), (0,4), and (-4,0)? (A) $(x-2)^2 + (y-2)^2 = \sqrt{8}$ (B) $(x-2)^2 + (y-2)^2 = 8$ (C) $(x+2)^2 + (y-2)^2 = 8$ (D) $(x+2)^2 + (y+2)^2 = \sqrt{8}$

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Quadratic Surface (pg. 18) & Tangent Line to Circle (pg. 23)

QUADRIC SURFACE (SPHERE)

The standard form of the equation is

$$(x-h)^2 + (y-k)^2 + (z-m)^2 = r^2$$

with center at (h, k, m).

In a three-dimensional space, the distance between two points is

 $d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

Length of the tangent line from a point on a circle to a point (x',y'):

$$t^2 = (x'-h)^2 + (y'-k)^2 - r^2$$







Area (pgs. 20-21)

Nomenclature

A = total surface area

- P = perimeter
- V = volume









$$\begin{split} P_{approx} &= 2\pi \sqrt{\left(a^2 + b^2\right)/2} \\ P &= \pi(a+b) \begin{cases} 1 + (1/2)^2 \lambda^2 + (1/2 \times 1/4)^2 \lambda^4 \\ + (1/2 \times 1/4 \times 3/6)^2 \lambda^6 + (1/2 \times 1/4 \times 3/6 \times 5/8)^2 \lambda^8 \\ + (1/2 \times 1/4 \times 3/6 \times 5/8 \times 7/10)^2 \lambda^{10} + \dots \end{cases} \\ \text{where} \\ \lambda &= (a-b)/(a+b) \end{split}$$

Circular Segment ♦



 $\phi = s/r = 2\left\{\arccos\left[(r-d)/r\right]\right\}$



 $V = 4\pi r^{3}/3 = \pi d^{3}/6$ $A = 4\pi r^{2} = \pi d^{2}$





P = 2(a + b) $d_1 = \sqrt{a^2 + b^2 - 2ab(\cos\phi)}$ $d_2 = \sqrt{a^2 + b^2 + 2ab(\cos\phi)}$ $d_1^2 + d_2^2 = 2(a^2 + b^2)$ $A = ah = ab(\sin\phi)$

If a = b, the parallelogram is a rhombus.

Regular Polygon (n equal sides)










Volume (pgs. 21-22)





$$V = (h/6)(A_1 + A_2 + 4A)$$

Right Circular Cone

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 $V = \left(\pi r^2 h\right)/3$ A = side area + base area $=\pi r \left(r + \sqrt{r^2 + h^2}\right)$ $A_{x}: A_{b} = x^{2}: h^{2}$



$$V = \pi r^2 h = \frac{\pi d^2 h}{4}$$

A = side area + end areas = $2\pi r(h + h)$

r)

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Paraboloid of Revolution



Right Circular Cylinder



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Algebra

- Logarithms
- Complex Numbers
- Polar Coordinates
- Roots
- Progressions and Series
 - Arithmetic Progression
 - Geometric Progression

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- Properties of Series
- Power Series

Logarithms (pg. 19)

LOGARITHMS

The logarithm of x to the Base b is defined by $\log_b (x) = c$, where $b^c = x$ Special definitions for b = e or b = 10 are: $\ln x$, Base = e $\log x$, Base = 10 To change from one Base to another: $\log_b x = (\log_a x)/(\log_a b)$ e.g., $\ln x = (\log_{10} x)/(\log_{10} e) = 2.302585 (\log_{10} x)$ Identities $\log_b b^n = n$ $\log_b b^n = n$ $\log_b x^c = c \log x; x^c = antilog (c \log x)$

 $\log xy = \log x + \log y$

 $\log_b b = 1; \log 1 = 0$

 $\log x/y = \log x - \log y$

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Complex Numbers (pg. 19)

Complex numbers may be designated in rectangular form or polar form. In rectangular form, a complex number is written in terms of its real and imaginary components.

z = a + jb, where

a = the real component,

- b = the imaginary component, and
- $j = \sqrt{-1}$ (some disciplines use $i = \sqrt{-1}$)

In polar form $z = c \angle \theta$ where $c = \sqrt{a^2 + b^2}$, $\theta = \tan^{-1} (b/a)$, $a = c \cos \theta$, and $b = c \sin \theta$. Complex numbers can be added and subtracted in rectangular form. If

$$z_{1} = a_{1} + jb_{1} = c_{1} (\cos \theta_{1} + j\sin \theta_{1})$$

= $c_{1} \angle \theta_{1}$ and
$$z_{2} = a_{2} + jb_{2} = c_{2} (\cos \theta_{2} + j\sin \theta_{2})$$

= $c_{2} \angle \theta_{2}$, then
$$z_{1} + z_{2} = (a_{1} + a_{2}) + j (b_{1} + b_{2})$$
 and
$$z_{1} - z_{2} = (a_{1} - a_{2}) + j (b_{1} - b_{2})$$

While complex numbers can be multiplied or divided in rectangular form, it is more convenient to perform these operations in polar form.

$$z_1 \times z_2 = (c_1 \times c_2) \angle (\theta_1 + \theta_2)$$
$$z_1/z_2 = (c_1/c_2) \angle (\theta_1 - \theta_2)$$

The complex conjugate of a complex number $z_1 = (a_1 + jb_1)$ is defined as $z_1^* = (a_1 - jb_1)$. The product of a complex number and its complex conjugate is $z_1z_1^* = a_1^2 + b_1^2$.

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Polar Coordinates (pg. 19)

Polar Coordinate System $x = r \cos \theta; y = r \sin \theta; \theta = \arctan(y/x)$ $r = |x + jy| = \sqrt{x^2 + y^2}$ $x + jy = r (\cos \theta + j \sin \theta) = re^{j\theta}$ $[r_1(\cos \theta_1 + j \sin \theta_1)][r_2(\cos \theta_2 + j \sin \theta_2)] =$ $r_1r_2[\cos(\theta_1 + \theta_2) + j \sin(\theta_1 + \theta_2)]$ $(x + jy)^n = [r (\cos \theta + j \sin \theta)]^n$ $= r^n(\cos n\theta + j \sin n\theta)$ $\frac{r_1(\cos \theta_1 + j \sin \theta_1)}{r_2(\cos \theta_2 + j \sin \theta_2)} = \frac{r_1}{r_2}[\cos(\theta_1 - \theta_2) + j \sin(\theta_1 - \theta_2)]$ Euler's Identity

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$e^{-j\theta} = \cos \theta - j \sin \theta$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}, \quad \sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

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The rectangular coordinates of a complex number are (4, 6). What are the complex number's approximate polar coordinates?

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(A) (4.0, 33°)
(B) (4.0, 56°)
(C) (7.2, 33°)
(D) (7.2, 56°)

The rectangular coordinates of a complex number are (4, 6). What are the complex number's approximate polar coordinates?

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(A) (4.0, 33°)
(B) (4.0, 56°)
(C) (7.2, 33°)
(D) (7.2, 56°)

If $j = \sqrt{-1}$, which of the following is equal to j^{j} ? (A) j^{2} (B) e^{2j} (C) -1(D) $e^{-\frac{\pi}{2}}$

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5<u>6</u>

If $j = \sqrt{-1}$, which of the following is equal to j^{j} ? (A) j^{2} (B) e^{2j} (C) -1(D) $e^{-\frac{\pi}{2}}$

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Roots: Quadratic Equation

What are the roots of the quadratic equation $-7x + x^2 = -10$?

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- (A) -5 and 2
- (B) -2 and 0.4
- (C) 0.4 and 2
- (D) 2 and 5

Roots: Quadratic Equation

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- (C) 0.4 and 2
- (D) 2 and 5

Progressions and Series (pg. 26)

Arithmetic Progression

To determine whether a given finite sequence of numbers is an arithmetic progression, subtract each number from the following number. If the differences are equal, the series is arithmetic.

- 1. The first term is *a*.
- 2. The common difference is d.
- 3. The number of terms is *n*.
- 4. The last or *n*th term is *l*.
- 5. The sum of *n* terms is *S*.

$$l = a + (n - 1)d$$

 $S = n(a + l)/2 = n [2a + (n - 1) d]/2$

Geometric Progression

To determine whether a given finite sequence is a geometric progression (G.P.), divide each number after the first by the preceding number. If the quotients are equal, the series is geometric:

- 1. The first term is *a*.
- 2. The common ratio is *r*.
- 3. The number of terms is *n*.
- 4. The last or *n*th term is *l*.
- 5. The sum of *n* terms is *S*.

$$l = ar^{n-1}$$

$$S = a (1 - r^n)/(1 - r); r \neq 1$$

$$S = (a - rl)/(1 - r); r \neq 1$$

limit
$$S_r = a/(1-r); r < 1$$

$$n \rightarrow \infty$$

A G.P. converges if |r| < 1 and it diverges if |r| > 1.

Properties of Series

$$\sum_{i=1}^{n} c = nc; \quad c = \text{ constant}$$

$$\sum_{i=1}^{n} cx_i = c \sum_{i=1}^{n} x_i$$

$$\sum_{i=1}^{n} (x_i + y_i - z_i) = \sum_{i=1}^{n} x_i + \sum_{i=1}^{n} y_i - \sum_{i=1}^{n} z_i$$

$$\sum_{x=1}^{n} x = (n + n^2)/2$$

Power Series

 $\sum_{i=0}^{\infty} a_i (x-a)^i$

- 1. A power series, which is convergent in the interval -R < x < R, defines a function of x that is continuous for all values of x within the interval and is said to represent the function in that interval.
- 2. A power series may be differentiated term by term within its interval of convergence. The resulting series has the same interval of convergence as the original series (except possibly at the end points of the series).
- 3. A power series may be integrated term by term provided the limits of integration are within the interval of convergence of the series.
- 4. Two power series may be added, subtracted, or multiplied, and the resulting series in each case is convergent, at least, in the interval common to the two series.
- 5. Using the process of long division (as for polynomials), two power series may be divided one by the other within their common interval of convergence.

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Trigonometry

- Degrees and Radians
- Plane Angles
- Triangles
 - Law of Sines
 - Law of Cosines
- Right Triangles
- General Triangles
- Trigonometric Identities

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Angles – Basic Knowledge



- acute angle: an angle less than 90° ($\pi/2$ rad)
- obtuse angle: an angle more than 90° ($\pi/2$ rad) but less than 180° (π rad)
- reflex angle: an angle more than 180° (π rad) but less than 360° (2π rad)
- related angle: an angle that differs from another by some multiple of 90° ($\pi/2$ rad)
- right angle: an angle equal to 90° ($\pi/2$ rad)
- straight angle: an angle equal to 180° (π rad); that is, a straight line



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Triangles (pg. 19)

TRIGONOMETRY





Triangles

The vertical angle to the top of a flagpole from point A on the ground is observed to be $37^{\circ} 11'$. The observer walks 17 m directly away from the flagpole from point A to point B and finds the new angle to be $25^{\circ} 43'$.



Triangles

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Identities (pg. 20)

Identities

 $\cos \theta = \sin (\theta + \pi/2) = -\sin (\theta - \pi/2)$ $\sin \theta = \cos (\theta - \pi/2) = -\cos (\theta + \pi/2)$ $\csc \theta = 1/\sin \theta$ $\sec \theta = 1/\cos \theta$ $\tan \theta = \sin \theta/\cos \theta$ $\cot \theta = 1/\tan \theta$ $\sin^2 \theta + \cos^2 \theta = 1$ $\tan^2 \theta + 1 = \sec^2 \theta$ $\cot^2 \theta + 1 = \csc^2 \theta$ $\sin (\alpha + \beta) = \sin \alpha \cos \beta + \cos \alpha \sin \beta$ $\cos (\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$ $\sin 2\alpha = 2 \sin \alpha \cos \alpha$ $\cos 2\alpha = \cos^2 \alpha - \sin^2 \alpha = 1 - 2 \sin^2 \alpha = 2 \cos^2 \alpha - 1$ $\tan 2\alpha = (2 \tan \alpha)/(1 - \tan^2 \alpha)$ $\cot 2\alpha = (\cot^2 \alpha - 1)/(2 \cot \alpha)$ $\tan (\alpha + \beta) = (\tan \alpha + \tan \beta)/(1 - \tan \alpha \tan \beta)$ $\cot (\alpha + \beta) = (\cot \alpha \cot \beta - 1)/(\cot \alpha + \cot \beta)$ $\sin (\alpha - \beta) = \sin \alpha \cos \beta - \cos \alpha \sin \beta$ $\cos (\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta$ $\tan (\alpha - \beta) = (\tan \alpha - \tan \beta)/(1 + \tan \alpha \tan \beta)$ $\cot (\alpha - \beta) = (\cot \alpha \cot \beta + 1)/(\cot \beta - \cot \alpha)$ $\sin(\alpha/2) = \pm \sqrt{(1 - \cos \alpha)/2}$ $\cos(\alpha/2) = \pm \sqrt{(1 + \cos \alpha)/2}$ $\tan \left(\frac{\alpha}{2} \right) = \pm \sqrt{\frac{1 - \cos \alpha}{1 + \cos \alpha}}$ $\cot(\alpha/2) = \pm \sqrt{(1 + \cos \alpha)/(1 - \cos \alpha)}$ $\sin \alpha \sin \beta = (1/2) [\cos (\alpha - \beta) - \cos (\alpha + \beta)]$ $\cos \alpha \cos \beta = (1/2)[\cos (\alpha - \beta) + \cos (\alpha + \beta)]$ $\sin \alpha \cos \beta = (1/2) [\sin (\alpha + \beta) + \sin (\alpha - \beta)]$ $\sin \alpha + \sin \beta = 2 \sin \left[(1/2)(\alpha + \beta) \right] \cos \left[(1/2)(\alpha - \beta) \right]$ $\sin \alpha - \sin \beta = 2 \cos \left[(1/2)(\alpha + \beta) \right] \sin \left[(1/2)(\alpha - \beta) \right]$ $\cos \alpha + \cos \beta = 2 \cos \left[(1/2)(\alpha + \beta) \right] \cos \left[(1/2)(\alpha - \beta) \right]$ $\cos \alpha - \cos \beta = -2 \sin \left[(1/2)(\alpha + \beta) \right] \sin \left[(1/2)(\alpha - \beta) \right]$

















Calculus

- Differential Calculus
- Critical Points
- Partial Derivatives
- Curvature
- Limits
- Integral Calculus
- Centroids and Moments of Inertia

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• Taylor Series

Differential Calculus (pg. 23)

The Derivative

For any function y = f(x), the derivative $= D_x y = \frac{dy}{dx} = y'$

$$y' = \lim_{\Delta x \to 0} \left[(\Delta y) / (\Delta x) \right]$$
$$= \lim_{\Delta x \to 0} \left\{ \left[f(x + \Delta x) - f(x) \right] / (\Delta x) \right\}$$

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y' = the slope of the curve f(x).

Derivative and Integral Table (pg. 25)

1. dc/dx = 02. dx/dx = 13. d(cu)/dx = c du/dx4. d(u+v-w)/dx = du/dx + dv/dx - dw/dx5. d(uv)/dx = u dv/dx + v du/dx6. d(uvw)/dx = uv dw/dx + uw dv/dx + vw du/dx7. $\frac{d(u/v)}{d(u/v)} = \frac{v \, du/dx - u \, dv/dx}{u \, dv/dx}$ dx 8. $d(u^n)/dx = nu^{n-1} du/dx$ 9. $d[f(u)]/dx = \{d[f(u)]/du\} du/dx$ 10. du/dx = 1/(dx/du)11. $\frac{d(\log_a u)}{dr} = (\log_a e) \frac{1}{u} \frac{du}{dr}$ 12. $\frac{d(\ln u)}{du} = \frac{1}{u} \frac{du}{du}$ 13. $\frac{d(a^u)}{du} = (\ln a)a^u \frac{du}{du}$ 14. $d(e^u)/dx = e^u du/dx$ 15. $d(u^{\nu})/dx = \nu u^{\nu-1} du/dx + (\ln u) u^{\nu} d\nu/dx$ 16. $d(\sin u)/dx = \cos u \, du/dx$ 17. $d(\cos u)/dx = -\sin u \, du/dx$ 18. $d(\tan u)/dx = \sec^2 u \, du/dx$ 19. $d(\cot u)/dx = -\csc^2 u \, du/dx$ 20. $d(\sec u)/dx = \sec u \tan u \, du/dx$ 21. $d(\csc u)/dx = -\csc u \cot u du/dx$ 21. $d(\csc u)/dx = -\csc u \cot u \, du/dx$ 22. $\frac{d(\sin^{-1}u)}{dx} = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}$ $(-\pi/2 \le \sin^{-1}u \le \pi/2)$ 20. $\int \tan^2 x \, dx = \ln|\csc x|$ 21. $d(\sin^2 x \, dx = -\ln|\csc x|)$ 22. $d(\sin^2 x \, dx = -\ln|\csc x|)$ 23. $\int \tan^2 x \, dx = -\ln|\csc x|$ 24. $(-\pi/2 \le \sin^{-1}u \le \pi/2)$ 25. $\int \tan^2 x \, dx = -\ln|\csc x|$ 26. $\int \tan^2 x \, dx = -\ln|\csc x|$ 27. $\int \tan^2 x \, dx = -\ln|\csc x|$ $23. \quad \frac{d(\cos^{-1}u)}{dx} = -\frac{1}{\sqrt{1-u^2}} \frac{du}{dx} \qquad (0 \le \cos^{-1}u \le \pi) \qquad 21. \quad \int \cot^2 x \, dx = -\cot x - x$ $23. \quad \frac{d(\cos^{-1}u)}{dx} = -\frac{1}{\sqrt{1-u^2}} \frac{du}{dx} \qquad (0 \le \cos^{-1}u \le \pi) \qquad 22. \quad \int e^{ax} \, dx = (1/a) \, e^{ax}$ $23. \quad \int x \, dx = (a^{ax}/a^2)(ax-1) \qquad 23. \quad \int x \, dx = x \, [\ln(x)-1] \qquad (x > 0)$ $25. \quad \frac{d(\cos^{-1}u)}{dx} = -\frac{1}{1+u^2} \frac{du}{dx} \qquad (0 < \cot^{-1}u < \pi) \qquad 25. \quad \int \frac{dx}{a^2 + x^2} = \frac{1}{a} \tan^{-1} \frac{x}{a} \qquad (a \ne 0)$ $26. \quad \frac{d(\sec^{-1}u)}{dx} = \frac{1}{u\sqrt{u^2-1}} \frac{du}{dx} \qquad 26. \quad \int \frac{dx}{ax^2 + c} = \frac{1}{\sqrt{ac}} \tan^{-1} \left(x\sqrt{\frac{a}{c}}\right), \qquad (a \ge 1)$ $u\sqrt{u^{2}-1} \frac{dx}{dx}$ $(0 < \sec^{-1}u < \pi/2)(-\pi \le \sec^{-1}u < -\pi/2)$ $27a \int \frac{dx}{ax^{2}+c} = \frac{1}{\sqrt{ac}} \tan^{-1}\left(x\sqrt{\frac{a}{c}}\right), \quad (a > 0, c = 1)$ $27a \int \frac{dx}{ax^{2}+bx+c} = \frac{2}{\sqrt{4ac-b^{2}}} \tan^{-1}\frac{2ax+b}{\sqrt{4ac-b^{2}}}$ $(0 < \csc^{-1}u \le \pi/2)(-\pi < \csc^{-1}u \le -\pi/2)$

1. $\int df(x) = f(x)$ 2. $\int dx = x$ 3. $\int a f(x) dx = a \int f(x) dx$ 4. $\int [u(x) \pm v(x)] dx = \int u(x) dx \pm \int v(x) dx$ 5. $\int x^m dx = \frac{x^{m+1}}{m+1}$ $(m \neq -1)$ 6. $\int u(x) dv(x) = u(x) v(x) - \int v(x) du(x)$ 7. $\int \frac{dx}{ax+b} = \frac{1}{a} \ln|ax+b|$ 8. $\int \frac{dx}{\sqrt{x}} = 2\sqrt{x}$ 9. $\int a^x dx = \frac{a^x}{\ln a}$ 10. $\int \sin x \, dx = -\cos x$ 11. $\int \cos x \, dx = \sin x$ 12. $\int \sin^2 x dx = \frac{x}{2} - \frac{\sin 2x}{4}$ 13. $\int \cos^2 x dx = \frac{x}{2} + \frac{\sin 2x}{4}$ 14. $\int x \sin x \, dx = \sin x - x \cos x$ 15. $\int x \cos x \, dx = \cos x + x \sin x$ 16. $\int \sin x \cos x \, dx = (\sin^2 x)/2$ 17. $\int \sin ax \cos bx \, dx = -\frac{\cos(a-b)x}{2(a-b)} - \frac{\cos(a+b)x}{2(a+b)} \left(a^2 \neq b^2\right)$ 18. $\int \tan x \, dx = -\ln \left| \cos x \right| = \ln \left| \sec x \right|$ 19. $\int \cot x \, dx = -\ln \left| \csc x \right| = \ln \left| \sin x \right|$ 26. $\int \frac{dx}{ax^2 + a} = \frac{1}{\sqrt{aa}} \tan^{-1}\left(x\sqrt{\frac{a}{c}}\right), \qquad (a > 0, c > 0)$ $(4ac - h^2 > 0)$ $27b.\int \frac{dx}{ax^2 + bx + c} = \frac{1}{\sqrt{b^2 - 4ac}} \ln \left| \frac{2ax + b - \sqrt{b^2 - 4ac}}{2ax + b + \sqrt{b^2 - 4ac}} \right|^2$ 27c. $\int \frac{dx}{ax^2 + bx + c} = -\frac{2}{2ax + b},$ $(b^2 - 4ac = 0)$

Derivatives of polynomials missing

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- Product rule of differentiation
- Integration by parts





Differential Calculus

Evaluate dy/dx for the following expression.

 $y = e^{-x} \sin 2x$

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(A)
$$e^{-x}(2\cos 2x - \sin 2x)$$

- (B) $-e^{-x}(2\sin 2x + \cos 2x)$
- (C) $e^{-x}(2\sin 2x + \cos 2x)$

(D) $-e^{-x}(2\cos 2x - \sin 2x)$

Differential Calculus

Evaluate dy/dx for the following expression.

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$$e^{-x}(2\cos 2x - \sin 2x)$$

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(C)
$$e^{-x}(2\sin 2x + \cos 2x)$$

(D)
$$-e^{-x}(2\cos 2x - \sin 2x)$$

91 Critical Points (pg. 23) Test for a Maximum y = f(x) is a maximum for x = a, if f'(a) = 0 and f''(a) < 0. Test for a Minimum y = f(x) is a minimum for x = a, if f'(a) = 0 and f''(a) > 0. Test for a Point of Inflection y = f(x) has a point of inflection at x = a, if f''(a) = 0, and if f''(x) changes sign as x increases through x = a.





94 **Critical Points** What is the minimum value of the function f(x) = $3x^2 + 3x - 5?$ (A) -12.0 (B) -8.0 (C) -5.75 (D) -5.00

95 **Critical Points** What is the minimum value of the function f(x) = $3x^2 + 3x - 5?$ (A) -12.0 (B) -8.0 (C) -5.75(D) -5.00

Partial Derivatives (pg. 23)

The Partial Derivative

In a function of two independent variables x and y, a derivative with respect to one of the variables may be found if the other variable is *assumed* to remain constant. If y is kept *fixed*, the function

z = f(x, y)

becomes a function of the *single variable x*, and its derivative (if it exists) can be found. This derivative is called the *partial derivative of z with respect to x*. The partial derivative with respect to x is denoted as follows:

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$$\frac{\partial z}{\partial x} = \frac{\partial f(x, y)}{\partial x}$$



What is the partial derivative with respect to x of the following function?

 $z = e^{xy}$





Curvature (pg. 24)



The curvature K of a curve at P is the limit of its average curvature for the arc PQ as Q approaches P. This is also expressed as: the curvature of a curve at a given point is the rate-of-change of its inclination with respect to its arc length.

$$K = \lim_{\Delta s \to 0} \frac{\Delta \alpha}{\Delta s} = \frac{d\alpha}{ds}$$

Curvature in Rectangular Coordinates

$$K = \frac{y''}{\left[1 + (y')^2\right]^{3/2}}$$

When it may be easier to differentiate the function with respect to y rather than x, the notation x' will be used for the derivative.

$$x' = dx/dy$$

 $K = \frac{-x''}{\left[1 + (x')^2\right]^{3/2}}$

The Radius of Curvature

The *radius of curvature* R at any point on a curve is defined as the absolute value of the reciprocal of the curvature K at that point.

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$$R = \frac{1}{|K|} \qquad (K \neq 0)$$
$$R = \left| \frac{\left[1 + (y')^2 \right]^{3/2}}{|y''|} \right| \quad (y'' \neq 0)$$





Limits (pg. 24)

L'Hospital's Rule (L'Hôpital's Rule)

If the fractional function f(x)/g(x) assumes one of the indeterminate forms 0/0 or ∞/∞ (where α is finite or infinite), then

 $\lim_{x \to \alpha} \frac{f(x)}{g(x)}$

is equal to the first of the expressions

$$\lim_{x \to \alpha} \frac{f'(x)}{g'(x)}, \lim_{x \to \alpha} \frac{f''(x)}{g''(x)}, \lim_{x \to \alpha} \frac{f'''(x)}{g'''(x)}$$

which is not indeterminate, provided such first indicated limit exists.

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Integral Calculus (pg. 24)

INTEGRAL CALCULUS

The definite integral is defined as:

 $\lim_{n \to \infty} \sum_{i=1}^{n} f(x_i) \Delta x_i = \int_a^b f(x) dx$

Also, $\Delta x_i \rightarrow 0$ for all *i*.

A table of derivatives and integrals is available in the Derivatives and Indefinite Integrals section. The integral equations can be used along with the following methods of integration:

A. Integration by Parts (integral equation #6),

- B. Integration by Substitution, and
- C. Separation of Rational Fractions into Partial Fractions.





Derivative and Integral Table (pg. 25)

1. dc/dx = 01. $\int df(x) = f(x)$ 2. dx/dx = 12. $\int dx = x$ 3. d(cu)/dx = c du/dx3. $\int a f(x) dx = a \int f(x) dx$ 4. d(u + v - w)/dx = du/dx + dv/dx - dw/dx4. $\int [u(x) \pm v(x)] dx = \int u(x) dx \pm \int v(x) dx$ 5. d(uv)/dx = u dv/dx + v du/dx5. $\int x^m dx = \frac{x^{m+1}}{m+1}$ $(m \neq -1)$ 6. d(uvw)/dx = uv dw/dx + uw dv/dx + vw du/dx7. $\frac{d(u/v)}{d(u/v)} = \frac{v \, du/dx - u \, dv/dx}{u \, dv/dx}$ 6. $\int u(x) dv(x) = u(x) v(x) - \int v(x) du(x)$ 7. $\int \frac{dx}{ax+b} = \frac{1}{a} \ln|ax+b|$ 8. $d(u^n)/dx = nu^{n-1} du/dx$ 9. $d[f(u)]/dx = \{d[f(u)]/du\} du/dx$ 8. $\int \frac{dx}{\sqrt{x}} = 2\sqrt{x}$ 10. du/dx = 1/(dx/du)11. $\frac{d(\log_a u)}{dr} = (\log_a e) \frac{1}{u} \frac{du}{dr}$ 9. $\int a^x dx = \frac{a^x}{\ln a}$ 10. $\int \sin x \, dx = -\cos x$ 12. $\frac{d(\ln u)}{dr} = \frac{1}{u} \frac{du}{dr}$ 11. $\int \cos x \, dx = \sin x$ 13. $\frac{d(a^u)}{dx} = (\ln a)a^u \frac{du}{dx}$ 12. $\int \sin^2 x dx = \frac{x}{2} - \frac{\sin 2x}{4}$ 14. $d(e^u)/dx = e^u du/dx$ 13. $\int \cos^2 x \, dx = \frac{x}{2} + \frac{\sin 2x}{4}$ 15. $d(u^{\nu})/dx = \nu u^{\nu-1} du/dx + (\ln u) u^{\nu} d\nu/dx$ 14. $\int x \sin x \, dx = \sin x - x \cos x$ 16. $d(\sin u)/dx = \cos u \, du/dx$ 15. $\int x \cos x \, dx = \cos x + x \sin x$ 17. $d(\cos u)/dx = -\sin u \, du/dx$ 16. $\int \sin x \cos x \, dx = (\sin^2 x)/2$ 18. $d(\tan u)/dx = \sec^2 u \, du/dx$ 17. $\int \sin ax \cos bx \, dx = -\frac{\cos(a-b)x}{a^2 + b^2} - \frac{\cos(a+b)x}{a^2 + b^2} (a^2 \neq b^2)$ 19. $d(\cot u)/dx = -\csc^2 u \, du/dx$ 2(a - b)2(a + b)20. $d(\sec u)/dx = \sec u \tan u \, du/dx$ 18. $\int \tan x \, dx = -\ln \left| \cos x \right| = \ln \left| \sec x \right|$ 21. $d(\csc u)/dx = -\csc u \cot u \, du/dx$ 22. $\frac{d(\sin^{-1}u)}{dx} = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}$ $(-\pi/2 \le \sin^{-1}u \le \pi/2)$ 23. $\frac{d(\sin^{-1}u)}{dx} = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}$ $(-\pi/2 \le \sin^{-1}u \le \pi/2)$ 20. $\int \tan^2 x \, dx = \tan x - x$ 19. $\int \cot x \, dx = -\ln \left| \csc x \right| = \ln \left| \sin x \right|$ 23. $\frac{d(\cos^{-1}u)}{dx} = -\frac{1}{\sqrt{1-u^2}} \frac{du}{dx} \qquad (0 \le \cos^{-1}u \le \pi) \qquad 21. \int \cot^2 x \, dx = -\cot x - x \\ 22. \int e^{ax} \, dx = (1/a) e^{ax} \\ 23. \int x e^{ax} \, dx = (e^{ax}/a^2)(ax-1) \\ 24. \frac{d(\tan^{-1}u)}{dx} = \frac{1}{1+u^2} \frac{du}{dx} \qquad (-\pi/2 < \tan^{-1}u < \pi/2) \qquad 24. \int \ln x \, dx = x [\ln(x) - 1] \end{cases}$ 21. $\int \cot^2 x \, dx = -\cot x - x$ (x > 0) $25. \quad \frac{d(\cot^{-1}u)}{dx} = -\frac{1}{1+u^{2}} \frac{du}{dx} \qquad (0 < \cot^{-1}u < \pi) \qquad 25. \quad \int \frac{dx}{a^{2}+x^{2}} = \frac{1}{a} \tan^{-1} \frac{x}{a} \qquad (a \neq 0)$ $26. \quad \frac{d(\sec^{-1}u)}{dx} = \frac{1}{u\sqrt{u^{2}-1}} \frac{du}{dx} \qquad 26. \quad \int \frac{dx}{ax^{2}+c} = \frac{1}{\sqrt{ac}} \tan^{-1} \left(x\sqrt{\frac{a}{c}}\right), \qquad (a \neq 0)$ $26. \ \frac{d(\sec^{-1}u)}{dx} = \frac{1}{u\sqrt{u^2 - 1}} \frac{du}{dx}$ $26. \ \int \frac{dx}{ax^2 + c} = \frac{1}{\sqrt{ac}} \tan^{-1}\left(x\sqrt{\frac{a}{c}}\right),$ (a > 0, c >26. $\int \frac{dx}{ax^2 + c} = \frac{1}{\sqrt{aa}} \tan^{-1} \left(x \sqrt{\frac{a}{c}} \right), \qquad (a > 0, c > 0)$ $\left(4ac - b^2 > 0\right)$ $27b.\int \frac{dx}{ax^2 + bx + c} = \frac{1}{\sqrt{b^2 - 4ac}} \ln \left| \frac{2ax + b - \sqrt{b^2 - 4ac}}{2ax + b + \sqrt{b^2 - 4ac}} \right|^2$ $(0 < \csc^{-1}u \le \pi/2)(-\pi < \csc^{-1}u \le -\pi/2)$ $27c. \int \frac{dx}{ax^2 + bx + c} = -\frac{2}{2ax + b}, \qquad (b^2 - 4ac = 0)$

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Centroids and Moments of Inertia (pg. 26)

The *location of the centroid of an area*, bounded by the axes and the function y = f(x), can be found by integration.

$$x_{c} = \frac{\int x dA}{A}$$
$$y_{c} = \frac{\int y dA}{A}$$
$$A = \int f(x) dx$$
$$dA = f(x) dx = g(y) dy$$

10

The *first moment of area* with respect to the *y*-axis and the *x*-axis, respectively, are:

$$M_{y} = \int x \, dA = x_{c}A$$
$$M_{x} = \int y \, dA = y_{c}A$$

The moment of inertia (second moment of area) with respect to the y-axis and the x-axis, respectively, are:

$$I_{y} = \int x^{2} dA$$
$$I_{x} = \int y^{2} dA$$

The moment of inertia taken with respect to an axis passing through the area's centroid is the *centroidal moment of inertia*. The *parallel axis theorem* for the moment of inertia with respect to another axis parallel with and located d units from the centroidal axis is expressed by

$$I_{\text{parallel axis}} = I_c + Ad^2$$

In a plane, $J = \int r^2 dA = I_x + I_y$

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Centroids and Moments of Inertia

What is most nearly the x-coordinate of the centroid of the area bounded by y=0, f(x), x=0, and x=20?

$$f(x) = x^3 + 7x^2 - 5x + 6$$

(A) 7.6
(B) 9.4
(C) 14
(D) 16

11 0

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11 2

Centroids and Moments of Inertia

The moment of inertia about the x'-axis of the cross section shown is 334000 cm⁴. The cross-sectional area is 86 cm², and the thicknesses of the web and the flanges are the same.



(A) $2.4 \times 10^4 \text{ cm}^4$ (B) $7.4 \times 10^4 \text{ cm}^4$ (C) $2.0 \times 10^5 \text{ cm}^4$ (D) $6.4 \times 10^5 \text{ cm}^4$

What is most nearly the moment of inertia about the centroidal axis?

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Centroids and Moments of Inertia

The moment of inertia about the x'-axis of the cross section shown is 334000 cm⁴. The cross-sectional area is 86 cm², and the thicknesses of the web and the flanges are the same.



(A)	$2.4 \times$	$10^4 \mathrm{~cm}^4$
(B)	$7.4 \times$	$10^4 \mathrm{~cm}^4$
(C)	$2.0 \times$	$10^5~{ m cm}^4$
(D)	6.4 ×	$10^5~{ m cm}^4$

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What is most nearly the moment of inertia about the centroidal axis?

Taylor Series (pg. 26)

Taylor's Series

$$f(x) = f(a) + \frac{f'(a)}{1!}(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x - a)^n + \dots$$

is called *Taylor's series*, and the function f(x) is said to be expanded about the point *a* in a Taylor's series.

If a = 0, the Taylor's series equation becomes a *Maclaurin's* series.

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Taylor Series

Taylor's series is used to expand the function f(x) about a=0 to obtain f(b).

$$f(x) = \frac{1}{3x^3 + 4x + 8}$$

What are the first two terms of Taylor's series?

(A)
$$\frac{1}{16} + \frac{b}{8}$$

(B) $\frac{1}{8} - \frac{b}{16}$
(C) $\frac{1}{8} + \frac{b}{16}$
(D) $\frac{1}{4} - \frac{b}{16}$

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(C) $\frac{1}{8} + \frac{b}{16}$
(D) $\frac{1}{4} - \frac{b}{16}$

Differential Equations

- Ordinary Linear Differential Equations
- 1st Order Homogenous ODEs
- 2nd Order Homogenous ODEs
- 1st Order Nonhomogeneous ODEs

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- Fourier Transform
- Fourier Series
- Laplace Transform

[°]Ordinary Linear Differential Eqn (pg. 27)

A common class of ordinary linear differential equations is

$$b_n \frac{d^n y(x)}{dx^n} + \dots + b_1 \frac{dy(x)}{dx} + b_0 y(x) = f(x)$$

where $b_n, \ldots, b_i, \ldots, b_1, b_0$ are constants.

11

When the equation is a homogeneous differential equation, f(x) = 0, the solution is

$$y_h(x) = C_1 e^{r_1 x} + C_2 e^{r_2 x} + \dots + C_i e^{r_i x} + \dots + C_n e^{r_n x}$$

where r_n is the *n*th distinct root of the characteristic polynomial P(x) with

$$P(r) = b_n r^n + b_{n-1} r^{n-1} + \dots + b_1 r + b_0$$

If the root $r_1 = r_2$, then $C_2 e^{r_2 x}$ is replaced with $C_2 x e^{r_1 x}$.

Higher orders of multiplicity imply higher powers of x. The complete solution for the differential equation is

$$y(x) = y_h(x) + y_p(x),$$

where $y_p(x)$ is any particular solution with f(x) present. If f(x) has $e^{r_n x}$ terms, then resonance is manifested. Furthermore, specific f(x) forms result in specific $y_p(x)$ forms, some of which are:

f(x)	$y_p(x)$
A	B
$Ae^{\alpha x}$	$Be^{\alpha x}, \ \alpha \neq r_n$
$A_1 \sin \omega x + A_2 \cos \omega x$	$B_1 \sin \omega x + B_2 \cos \omega x$

If the independent variable is time *t*, then transient dynamic solutions are implied.

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Ordinary Linear Differential Eqn

Which of the following is NOT a linear differential equation?

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(A)
$$5\frac{d^2y}{dt^2} - 8\frac{dy}{dt} + 16y = 4te^{-7t}$$

(B) $5\frac{d^2y}{dt^2} - 8t^2\frac{dy}{dt} + 16y = 0$
(C) $5\frac{d^2y}{dt^2} - 8\frac{dy}{dt} + 16y = \frac{dy}{dy}$
(D) $5\left(\frac{dy}{dt}\right)^2 - 8\frac{dy}{dt} + 16y = 0$

Ordinary Linear Differential Eqn

Which of the following is NOT a linear differential equation?

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(A)
$$5\frac{d^2y}{dt^2} - 8\frac{dy}{dt} + 16y = 4te^{-7t}$$

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(D) $5\left(\frac{dy}{dt}\right)^2 - 8\frac{dy}{dt} + 16y = 0$

1st Order Homogeneous ODE (pg. 27)

12 2

First-Order Linear Homogeneous Differential Equations with Constant Coefficients

y'+ay = 0, where *a* is a real constant: Solution, $y = Ce^{-at}$

where C = a constant that satisfies the initial conditions.



1st Order Homogeneous ODE

Which of the following is the general solution to the differential equation and boundary conditions?

$$\frac{dy}{dt} - 5y = 0$$
$$y(0) = 3$$

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(A) $-\frac{1}{3}e^{-5t}$ (B) $3e^{5t}$ (C) $5e^{-3t}$ (D) $\frac{1}{5}e^{-3t}$

1st Order Homogeneous ODE

Which of the following is the general solution to the differential equation and boundary conditions?

$$\frac{dy}{dt} - 5y = 0$$
$$y(0) = 3$$

(A)
$$-\frac{1}{3}e^{-5t}$$

(B) $3e^{5t}$
(C) $5e^{-3t}$
(D) $\frac{1}{5}e^{-3t}$

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2nd Order Homogeneous ODE (pg. 27)

Second-Order Linear Homogeneous Differential Equations with Constant Coefficients

An equation of the form

$$y''+ay'+by=0$$

can be solved by the method of undetermined coefficients where a solution of the form $y = Ce^{rx}$ is sought. Substitution of this solution gives

 $(r^2 + ar + b) Ce^{rx} = 0$

and since Ce^{rx} cannot be zero, the characteristic equation must vanish or

 $r^2 + ar + b = 0$

The roots of the characteristic equation are

$$r_{1,2} = \frac{-a \pm \sqrt{a^2 - 4b}}{2}$$

and can be real and distinct for $a^2 > 4b$, real and equal for $a^2 = 4b$, and complex for $a^2 < 4b$.

If $a^2 > 4b$, the solution is of the form (overdamped) $y = C_1 e^{r_1 x} + C_2 e^{r_2 x}$ If $a^2 = 4b$, the solution is of the form (critically damped) $y = (C_1 + C_2 x) e^{r_1 x}$ If $a^2 < 4b$, the solution is of the form (underdamped) $y = e^{\alpha x} (C_1 \cos \beta x + C_2 \sin \beta x)$, where $\alpha = -a/2$ $\beta = \frac{\sqrt{4b - a^2}}{2}$

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2nd Order Homogeneous ODE

What is the general solution to the following homogeneous differential equation?

$$y'' - 8y' + 16y = 0$$

(A)
$$y = C_1 e^{4x}$$

(B) $y = (C_1 + C_2 x) e^{4x}$
(C) $y = C_1 e^{-4x} + C_2 e^{4x}$
(D) $y = C_1 e^{2x} + C_2 e^{4x}$

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¹st Order Nonhomogeneous ODE (pg. 27)

First-Order Linear Nonhomogeneous Differential Equations

$$\tau \frac{dy}{dt} + y = Kx(t) \qquad x(t) = \begin{cases} A & t < 0 \\ B & t > 0 \end{cases}$$
$$y(0) = KA$$

τ is the time constant K is the gain The solution is

12

$$y(t) = KA + (KB - KA)\left(1 - \exp\left(\frac{-t}{\tau}\right)\right) \text{ or }$$
$$\frac{t}{\tau} = \ln\left[\frac{KB - KA}{KB - y}\right]$$

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1st Order Nonhomogeneous ODE

A spring-mass-dashpot system starting from a motionless state is acted upon by a step function. The response is described by the differential equation in which time, t, is given in seconds measured from the application of the ramp function.

$$\frac{dy}{dt} + 2y = 2u(0) \quad [y(0) = 0]$$

How long will it take for the system to reach 63% of its final value?

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(A) 0.25 s
(B) 0.50 s
(C) 1.0 s
(D) 2.0 s

1st Order Nonhomogeneous ODE

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Fourier Series (pg. 28)

Every periodic function f(t) which has the period $T = 2\pi/\omega_0$ and has certain continuity conditions can be represented by a series plus a constant

$$f(t) = a_0 + \sum_{n=1}^{\infty} [a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)]$$

The above holds if f(t) has a continuous derivative f'(t) for all *t*. It should be noted that the various sinusoids present in the series are orthogonal on the interval 0 to *T* and as a result the coefficients are given by

$$a_{0} = (1/T) \int_{0}^{T} f(t) dt$$

$$a_{n} = (2/T) \int_{0}^{T} f(t) \cos(n\omega_{0}t) dt \qquad n = 1, 2, ...$$

$$b_{n} = (2/T) \int_{0}^{T} f(t) \sin(n\omega_{0}t) dt \qquad n = 1, 2, ...$$

The constants a_n and b_n are the Fourier coefficients of f(t) then for the interval 0 to T and the corresponding series is called the Fourier series of f(t) over the same interval.

The integrals have the same value when evaluated over any interval of length T.

If a Fourier series representing a periodic function is truncated after term n = N the mean square value F_N^2 of the truncated series is given by Parseval's relation. This relation says that the mean-square value is the sum of the meansquare values of the Fourier components, or

$$F_N^2 = a_0^2 + (1/2) \sum_{n=1}^N (a_n^2 + b_n^2)$$

and the RMS value is then defined to be the square root of this quantity or $F_{\scriptscriptstyle N^*}$

Three useful and common Fourier series forms are defined in terms of the following graphs (with $\omega_0 = 2\pi/T$). Given:



$$f_{1}(t) = \sum_{\substack{n=1\\(n \text{ odd})}}^{\infty} (-1)^{(n-1)/2} (4V_{0}/n\pi) \cos(n\omega_{0}t)$$



Given:

$$f_{2}(t) = \frac{V_{0}\tau}{T} + \frac{2V_{0}\tau}{T}\sum_{n=1}^{\infty}\frac{\sin(n\pi\tau/T)}{(n\pi\tau/T)}\cos(n\omega_{0}t)$$
$$f_{2}(t) = \frac{V_{0}\tau}{T}\sum_{n=-\infty}^{\infty}\frac{\sin(n\pi\tau/T)}{(n\pi\tau/T)}e^{jn\omega_{0}t}$$

Given:



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Fourier Transform (pg. 27, 29)

FOURIER TRANSFORM

The Fourier transform pair, one form of which is

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$$
$$f(t) = \left[\frac{1}{2\pi} \right] \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$$

can be used to characterize a broad class of signal models in terms of their frequency or spectral content. Some useful transform pairs are:

f(t)	F (ω)
$\delta(t)$	1
<i>u</i> (<i>t</i>)	$\pi\delta(\omega) + 1/j\omega$
$u\left(t+\frac{\tau}{2}\right)-u\left(t-\frac{\tau}{2}\right)=r_{rect}\frac{t}{\tau}$	$\tau \frac{\sin(\omega \tau/2)}{\omega \tau/2}$
$e^{j\omega_o t}$	$2\pi\delta(\omega-\omega_o)$

Some mathematical liberties are required to obtain the second and fourth form. Other Fourier transforms are derivable from the Laplace transform by replacing s with $j\omega$ provided

$$f(t) = 0, t < 0$$
$$\int_0^\infty |f(t)| dt < \infty$$

The Fourier Transform and its Inverse

$$X(f) = \int_{-\infty}^{+\infty} x(t) e^{-j2\pi f t} dt$$
$$x(t) = \int_{-\infty}^{+\infty} X(f) e^{j2\pi f t} df$$

We say that *x*(*t*) and *X*(*f*) form a *Fourier transform pair*:

$$x(t) \leftrightarrow X(f)$$

Fourier Transform Pairs x(t)X(f)1 $\delta(f)$ $\delta(t)$ 1 $\frac{1}{2}\delta(f) + \frac{1}{j2\pi f}$ u(t) $\Pi(t/\tau)$ $\tau \operatorname{sinc}(\tau f)$ $\frac{1}{B}\Pi(f/B)$ sinc(Bt) $\Lambda(t/\tau)$ $\tau \operatorname{sinc}^2(\tau f)$ a > 0 $e^{-at}u(t)$ $a + i2\pi f$ $te^{-at}u(t)$ a > 0 $(a+j2\pi f)^2$ $\frac{2a}{a^2+(2\pi f)^2}$ $e^{-a|t|}$ a > 0 $\frac{\sqrt{\pi}}{a}e^{-(\pi f/a)^2}$ $e^{-(at)^2}$ $\frac{1}{2}[e^{j\theta}\delta(f-f_0)+e^{-j\theta}\delta(f+f_0)]$ $\cos(2\pi f_0 t + \theta)$ $\frac{1}{2j}[e^{j\theta}\delta(f-f_0)-e^{-j\theta}\delta(f+f_0)]$ $\sin(2\pi f_0 t + \theta)$ $f_s \sum_{k=-\infty}^{k=+\infty} \delta(f - kf_s) \quad f_s = \frac{1}{T_s}$ $\sum_{n=-\infty}^{n=+\infty} \delta(t-nT_s)$

Fourier T	ransform	Theorems
-----------	----------	----------

Linearity	ax(t) + by(t)	aX(f)+bY(f)
Scale change	x(at)	$\frac{1}{ a }X\left(\frac{f}{a}\right)$
Time reversal	x(-t)	X(-f)
Duality	X(t)	x(-f)
Time shift	$x(t-t_0)$	$X(f)e^{-j2\pi ft_0}$
Frequency shift	$x(t)e^{j2\pi f_0 t}$	$X(f-f_0)$
Modulation	$x(t)\cos 2\pi f_0 t$	$\frac{1}{2}X(f - f_0) + \frac{1}{2}X(f + f_0)$
Multiplication	x(t)y(t)	X(f) * Y(f)
Convolution	x(t) * y(t)	X(f)Y(f)
Differentiation	$\frac{d^n x(t)}{dt^n}$	$(j2\pi f)^n X(f)$
Integration	$\int_{-\infty}^{t} x(\lambda) d\lambda$	$\frac{1}{j2\pi f}X(f)$ $+\frac{1}{2}X(0)\delta(f)$



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Laplace Transform (pg. 30)

LAPLACE TRANSFORMS

The unilateral Laplace transform pair

$$F(s) = \int_{0^{-}}^{\infty} f(t) e^{-st} dt$$
$$f(t) = \frac{1}{2\pi j} \int_{\sigma - j\infty}^{\sigma + j\infty} F(s) e^{st} dt$$
where $s = \sigma + j\omega$

represents a powerful tool for the transient and frequency response of linear time invariant systems. Some useful Laplace transform pairs are:

f(t)	F(s)
$\delta(t)$, Impulse at $t = 0$	1
u(t), Step at $t = 0$	1/ <i>s</i>
t[u(t)], Ramp at $t = 0$	$1/s^{2}$
$e^{-\alpha t}$	$1/(s + \alpha)$
$te^{-\alpha t}$	$1/(s+\alpha)^2$
$e^{-\alpha t}\sin\beta t$	$\beta/[(s+\alpha)^2+\beta^2]$
$e^{-\alpha t}\cos\beta t$	$(s+\alpha)/[(s+\alpha)^2+\beta^2]$
$\frac{d^n f(t)}{dt^n}$	$s^{n}F(s) - \sum_{m=0}^{n-1} s^{n-m-1} \frac{d^{m}f(0)}{dt^{m}}$
$\int_0^t f(\tau) d\tau$	(1/s)F(s)
$\int_0^t x (t-\tau) h(\tau) d\tau$	H(s)X(s)
$f(t-\tau) u(t-\tau)$	$e^{-\tau s}F(s)$
$\lim_{t\to\infty} f(t)$	$\lim_{s\to 0} sF(s)$
$\lim_{t\to 0} f(t)$	$\lim_{s\to\infty} sF(s)$

The last two transforms represent the Final Value Theorem (F.V.T.) and Initial Value Theorem (I.V.T.), respectively. It is assumed that the limits exist.

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What is the Laplace transform of $f(t) = e^{-6t}$?

(A)
$$\frac{1}{s+6}$$

(B) $\frac{1}{s-6}$
(C) e^{-6+s}

(D) e^{6+s}

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(D) e^{6+s}

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What is the Laplace transform of the step function f(t)?

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$$f(t) = u(t-1) + u(t-2)$$
(A) $\frac{1}{s} + \frac{2}{s}$
(B) $\frac{e^{-s} + e^{-2s}}{s}$
(C) $1 + \frac{e^{-2s}}{s}$
(D) $\frac{e^s}{s} + \frac{e^{2s}}{s}$

What is the Laplace transform of the step function f(t)?

f(t) = u(t-1) + u(t-2)

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Linear Algebra & Vectors

- Matrix Arithmetic
- Matrix Transpose and Inverse
- Determinant of a Matrix
- Solving Systems of Linear Equations
- Vector Addition and Subtraction
- Vector Dot and Cross Products
- Vector Identities
- Gradient, Divergence, and Curl

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Matrix Arithmetic (pg. 30)

A matrix is an ordered rectangular array of numbers with *m* rows and *n* columns. The element a_{ij} refers to row *i* and column *j*.

Multiplication of Two Matrices

$$A = \begin{bmatrix} A & B \\ C & D \\ E & F \end{bmatrix} A_{3,2} \text{ is a 3-row, 2-column matrix}$$

$$\mathbf{B} = \begin{bmatrix} \mathbf{H} & \mathbf{I} \\ \mathbf{J} & \mathbf{K} \end{bmatrix} \quad \mathbf{B}_{2,2} \text{ is a 2-row, 2-column matrix}$$

In order for multiplication to be possible, the number of columns in A must equal the number of rows in B.

Multiplying matrix B by matrix A occurs as follows:

$$C = \begin{bmatrix} A & B \\ C & D \\ E & F \end{bmatrix} \cdot \begin{bmatrix} H & I \\ J & K \end{bmatrix}$$
$$C = \begin{bmatrix} (A \cdot H + B \cdot J) & (A \cdot I + B \cdot K) \\ (C \cdot H + D \cdot J) & (C \cdot I + D \cdot K) \\ (E \cdot H + F \cdot J) & (E \cdot I + F \cdot K) \end{bmatrix}$$

Matrix multiplication is not commutative.

Addition $\begin{bmatrix} A & B & C \\ D & E & F \end{bmatrix} + \begin{bmatrix} G & H & I \\ J & K & L \end{bmatrix} = \begin{bmatrix} A+G & B+H & C+I \\ D+J & E+K & F+L \end{bmatrix}$

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Matrix Arithmetic

What is the matrix product **AB** of matrices **A** and **B**?

$$\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 1 & 0 \end{bmatrix} \qquad \mathbf{B} = \begin{bmatrix} 4 & 3 \\ 2 & 1 \end{bmatrix}$$
(A)
$$\begin{bmatrix} 10 & 4 \\ 7 & 3 \end{bmatrix}$$
(B)
$$\begin{bmatrix} 11 & 4 \\ 5 & 2 \end{bmatrix}$$
(C)
$$\begin{bmatrix} 8 & 3 \\ 2 & 0 \end{bmatrix}$$
(D)
$$\begin{bmatrix} 10 & 7 \\ 4 & 3 \end{bmatrix}$$
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Matrix Arithmetic

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$$(C) \begin{bmatrix} 8 & 3 \\ 2 & 0 \end{bmatrix}$$

$$(D) \begin{bmatrix} 10 & 7 \\ 4 & 3 \end{bmatrix}$$
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Matrix Transpose and Inverse (pg. 30)

Identity Matrix

The matrix $I = (a_{ij})$ is a square $n \times n$ matrix with 1's on the diagonal and 0's everywhere else.

Matrix Transpose

Rows become columns. Columns become rows.

$$\mathbf{A} = \begin{bmatrix} \mathbf{A} & \mathbf{B} & \mathbf{C} \\ \mathbf{D} & \mathbf{E} & \mathbf{F} \end{bmatrix} \quad \mathbf{A}^{\mathrm{T}} = \begin{bmatrix} \mathbf{A} & \mathbf{D} \\ \mathbf{B} & \mathbf{E} \\ \mathbf{C} & \mathbf{F} \end{bmatrix}$$

Inverse []⁻¹ The inverse **B** of a square $n \times n$ matrix **A** is $B = A^{-1} = \frac{\operatorname{adj}(A)}{|A|}$, where

adj(A) = adjoint of A (obtained by replacing A^T elements with their cofactors) and |A| = determinant of A.

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 $[\mathbf{A}][\mathbf{A}]^{-1} = [\mathbf{A}]^{-1}[\mathbf{A}] = [\mathbf{I}]$ where **I** is the identity matrix.



What is the transpose of matrix **A**?

$$\mathbf{A} = \begin{bmatrix} 5 & 8 & 5 & 8 \\ 8 & 7 & 6 & 2 \end{bmatrix}$$



Using the property that $|\mathbf{AB}| = |\mathbf{A}||\mathbf{B}|$ for two square matrices, what is $|\mathbf{A}^{-1}|$ in terms of $|\mathbf{A}|$ for any invertible square matrix \mathbf{A} ?

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(A)
$$\frac{1}{|\mathbf{A}|}$$

(B) $\frac{1}{|\mathbf{A}^{-1}|}$
(C) $\frac{|\mathbf{A}|}{|\mathbf{A}^{-1}|}$
(D) $\frac{|\mathbf{A}^{-1}|}{|\mathbf{A}|}$

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The cofactor matrix of matrix A is C.

$$\mathbf{A} = \begin{bmatrix} 4 & 2 & 3 \\ 3 & 2 & 2 \\ 2 & 1 & 4 \end{bmatrix} \qquad \mathbf{C} = \begin{bmatrix} 6 & -8 & -1 \\ -5 & 10 & 0 \\ -2 & 1 & 2 \end{bmatrix}$$

(A)	0.25	0		٥Į	
	0	0.50		0	
	Lο	0	0.2	5	
(B)	$[0.25]{0.25}$	0.50	0.3	3]	
	0.33	0.50	0.5	0	
	0.50	1.0	0.2	5	
(C)	[1.2	$^{-1}$.0	-0.40	1
	-1.6	2	.0	0.20	
	-0.20)	0	0.40]
(D)	[0.80) 0	.40	-0.6	07
	0.20) -0	.40	0.4	0
	-0.40) ()	.60	0.8	0]

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What is the inverse of matrix **A**?

The cofactor matrix of matrix A is C.

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(A)
$$\begin{bmatrix} 0 & 0.50 & 0 \\ 0 & 0 & 0.25 \end{bmatrix}$$

(B)
$$\begin{bmatrix} 0.25 & 0.50 & 0.33 \\ 0.33 & 0.50 & 0.50 \\ 0.50 & 1.0 & 0.25 \end{bmatrix}$$

(C)
$$\begin{bmatrix} 1.2 & -1.0 & -0.40 \\ -1.6 & 2.0 & 0.20 \\ -0.20 & 0 & 0.40 \end{bmatrix}$$

(D)
$$\begin{bmatrix} 0.80 & 0.40 & -0.60 \\ 0.20 & -0.40 & 0.40 \\ -0.40 & 0.60 & 0.80 \end{bmatrix}$$

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Determinants (pg. 31)

A determinant of order n consists of n^2 numbers, called the *elements* of the determinant, arranged in n rows and n columns and enclosed by two vertical lines.

In any determinant, the *minor* of a given element is the determinant that remains after all of the elements are struck out that lie in the same row and in the same column as the given element. Consider an element which lies in the *j*th column and the *i*th row. The *cofactor* of this element is the value of the minor of the element (if i + j is *even*), and it is the negative of the value of the minor of the minor of the element (if i + j is *odd*).

If n is greater than 1, the *value* of a determinant of order n is the sum of the n products formed by multiplying each element of some specified row (or column) by its cofactor. This sum is called the *expansion of the determinant* [according to the elements of the specified row (or column)]. For a second-order determinant:

$$\begin{vmatrix} a_1 a_2 \\ b_1 b_2 \end{vmatrix} = a_1 b_2 - a_2 b_2$$

For a third-order determinant:

 $\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 b_2 c_3 + a_2 b_3 c_1 + a_3 b_1 c_2 - a_3 b_2 c_1 - a_2 b_1 c_3 - a_1 b_3 c_2$

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Determinants

For the following set of equations, what is the determinant of the coefficient matrix?

$$10x + 3y + 10z = 5$$
$$8x - 2y + 9z = 5$$
$$8x + y - 10z = 5$$

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(A) 598
(B) 620
(C) 714
(D) 806

Determinants

For the following set of equations, what is the determinant of the coefficient matrix?

$$10x + 3y + 10z = 5$$
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(B) 620
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¹⁵ Vector Addition and Subtraction (pg. 31)



Vector Addition and Subtraction

Find the unit vector (i.e., the direction vector) associated with the origin-based vector $18\mathbf{i} + 3\mathbf{j} + 29\mathbf{k}$.

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- (A) 0.525i + 0.088j + 0.846k
- (B) 0.892i + 0.178j + 0.416k
- (C) 1.342i + 0.868j + 2.437k
- (D) $6i + j + \frac{29}{3}k$



Find the unit vector (i.e., the direction vector) associated with the origin-based vector $18\mathbf{i} + 3\mathbf{j} + 29\mathbf{k}$.

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- (B) 0.892i + 0.178j + 0.416k
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- (D) $6i + j + \frac{29}{3}k$

Vector Addition and Subtraction

What is the sum of the two vectors $5\mathbf{i} + 3\mathbf{j} - 7\mathbf{k}$ and $10\mathbf{i} - 12\mathbf{j} + 5\mathbf{k}$?

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- (A) 8i 7j k
- (B) 10i 9j + 3k
- (C) 15i 9j 2k
- (D) 15i + 7j 3k

Vector Addition and Subtraction

What is the sum of the two vectors $5\mathbf{i} + 3\mathbf{j} - 7\mathbf{k}$ and $10\mathbf{i} - 12\mathbf{j} + 5\mathbf{k}$?

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- (A) 8i 7j k
- (B) 10i 9j + 3k
- (C) 15i 9j 2k
- (D) 15i + 7j 3k

Vector Dot and Cross Products (pg. 31)

The *dot product* is a *scalar product* and represents the projection of **B** onto **A** times $|\mathbf{A}|$. It is given by

 $\mathbf{A} \cdot \mathbf{B} = a_x b_x + a_y b_y + a_z b_z$ $= |\mathbf{A}| |\mathbf{B}| \cos \theta = \mathbf{B} \cdot \mathbf{A}$

The cross product is a vector product of magnitude $|\mathbf{B}| |\mathbf{A}| \sin \theta$ which is perpendicular to the plane containing **A** and **B**. The product is

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix} = -\mathbf{B} \times \mathbf{A}$$

The sense of $\mathbf{A} \times \mathbf{B}$ is determined by the right-hand rule. $\mathbf{A} \times \mathbf{B} = |\mathbf{A}| |\mathbf{B}| \mathbf{n} \sin \theta$, where $\mathbf{n} =$ unit vector perpendicular to the plane of \mathbf{A} and \mathbf{B} .

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Vector Dot and Cross Products

What is the dot product, $A \cdot B$, of the vectors A = 2i + 4j + 8k and B = -2i + j - 4k? (A) -4i + 4j - 32k(B) -4i - 4j - 32k(C) -40(D) -32

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Vector Dot and Cross Products

What is the dot product, $A \cdot B$, of the vectors A = 2i + 4j + 8k and B = -2i + j - 4k? (A) -4i + 4j - 32k(B) -4i - 4j - 32k(C) -40(D) -32

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Vector Identities (pg. 31)

```
\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}; \mathbf{A} \cdot (\mathbf{B} + \mathbf{C}) = \mathbf{A} \cdot \mathbf{B} + \mathbf{A} \cdot \mathbf{C}
\mathbf{A} \cdot \mathbf{A} = |\mathbf{A}|^2
\mathbf{i} \cdot \mathbf{i} = \mathbf{j} \cdot \mathbf{j} = \mathbf{k} \cdot \mathbf{k} = 1
\mathbf{i} \cdot \mathbf{j} = \mathbf{j} \cdot \mathbf{k} = \mathbf{k} \cdot \mathbf{i} = 0
If \mathbf{A} \cdot \mathbf{B} = 0, then either \mathbf{A} = 0, \mathbf{B} = 0, or \mathbf{A} is perpendicular
to B.
\mathbf{A} \times \mathbf{B} = -\mathbf{B} \times \mathbf{A}
\mathbf{A} \times (\mathbf{B} + \mathbf{C}) = (\mathbf{A} \times \mathbf{B}) + (\mathbf{A} \times \mathbf{C})
(\mathbf{B} + \mathbf{C}) \times \mathbf{A} = (\mathbf{B} \times \mathbf{A}) + (\mathbf{C} \times \mathbf{A})
\mathbf{i} \times \mathbf{i} = \mathbf{j} \times \mathbf{j} = \mathbf{k} \times \mathbf{k} = \mathbf{0}
\mathbf{i} \times \mathbf{j} = \mathbf{k} = -\mathbf{j} \times \mathbf{i}; \mathbf{j} \times \mathbf{k} = \mathbf{i} = -\mathbf{k} \times \mathbf{j}
\mathbf{k} \times \mathbf{i} = \mathbf{j} = -\mathbf{i} \times \mathbf{k}
If \mathbf{A} \times \mathbf{B} = \mathbf{0}, then either \mathbf{A} = \mathbf{0}, \mathbf{B} = \mathbf{0}, or \mathbf{A} is parallel to \mathbf{B}.
\nabla^2 \phi = \nabla \cdot (\nabla \phi) = (\nabla \cdot \nabla) \phi
\nabla \times \nabla \phi = \mathbf{0}
\nabla \cdot (\nabla \times \mathbf{A}) = \mathbf{0}
\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}
```

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Vector Identities

What is the dot product $\mathbf{A} \cdot \mathbf{B}$ of unit vectors $\mathbf{A} = 3\mathbf{i}$ and $\mathbf{B} = 2\mathbf{i}$?

(B)
$$-5$$

(D) 6

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Vector Identities

What is the dot product $\mathbf{A} \cdot \mathbf{B}$ of unit vectors $\mathbf{A} = 3\mathbf{i}$ and $\mathbf{B} = 2\mathbf{i}$?

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Gradient, Divergence, and Curl (pg. 31)

Gradient, Divergence, and Curl $\nabla \phi = \left(\frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}\right)\phi$ $\nabla \cdot \mathbf{V} = \left(\frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}\right) \cdot \left(V_{1}\mathbf{i} + V_{2}\mathbf{j} + V_{3}\mathbf{k}\right)$ $\nabla \times \mathbf{V} = \left(\frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}\right) \times \left(V_{1}\mathbf{i} + V_{2}\mathbf{j} + V_{3}\mathbf{k}\right)$

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The Laplacian of a scalar function ϕ is $\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$



What is the divergence of the following vector field?

$$\mathbf{V} = 2x\mathbf{i} + 2y\mathbf{j}$$

(A) 0
(B) 2
(C) 3
(D) 4

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Determine the curl of the vector function $\mathbf{V}(x, y, z)$.

$$\mathbf{V}(x, y, z) = 3x^2\mathbf{i} + 7e^x y\mathbf{j}$$

(A) $7e^x y$ (B) $7e^x y \mathbf{i}$ (C) $7e^x y \mathbf{j}$ (D) $7e^x y \mathbf{k}$

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Determine the curl of the vector function $\mathbf{V}(x, y, z)$.

$$\mathbf{V}(x, y, z) = 3x^2\mathbf{i} + 7e^x y\mathbf{j}$$

(A) $7e^{x}y$ (B) $7e^{x}yi$ (C) $7e^{x}yj$ (D) $7e^{x}yk$

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Determine the Laplacian of the scalar function $\frac{1}{3}x^3 - 9y + 5$ at the point (3, 2, 7). (A) 0 (B) 1 (C) 6 (D) 9

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Determine the Laplacian of the scalar function $\frac{1}{3}x^3 - 9y + 5$ at the point (3, 2, 7). (A) 0 (B) 1 (C) 6 (D) 9

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